

# NASA ROVER 2

Mutlaq Aldossari, Abdullah Aloqayli, Abdulrahman  
Alsarhan, Adam Anawalt, Sean Bingham, Dustin Shepherd,  
LA Veatch

# NASA Human Exploration Rover Challenge Competition Background

- Located at the US Space and Rocket Center in Huntsville, AL
- Competition March 30 – April 1
- Students design and manufacture vehicle



# Course Obstacles

## Competition

- Create a human powered vehicle, carried by two students, one male, one female.
- Traverse a half mile obstacle course

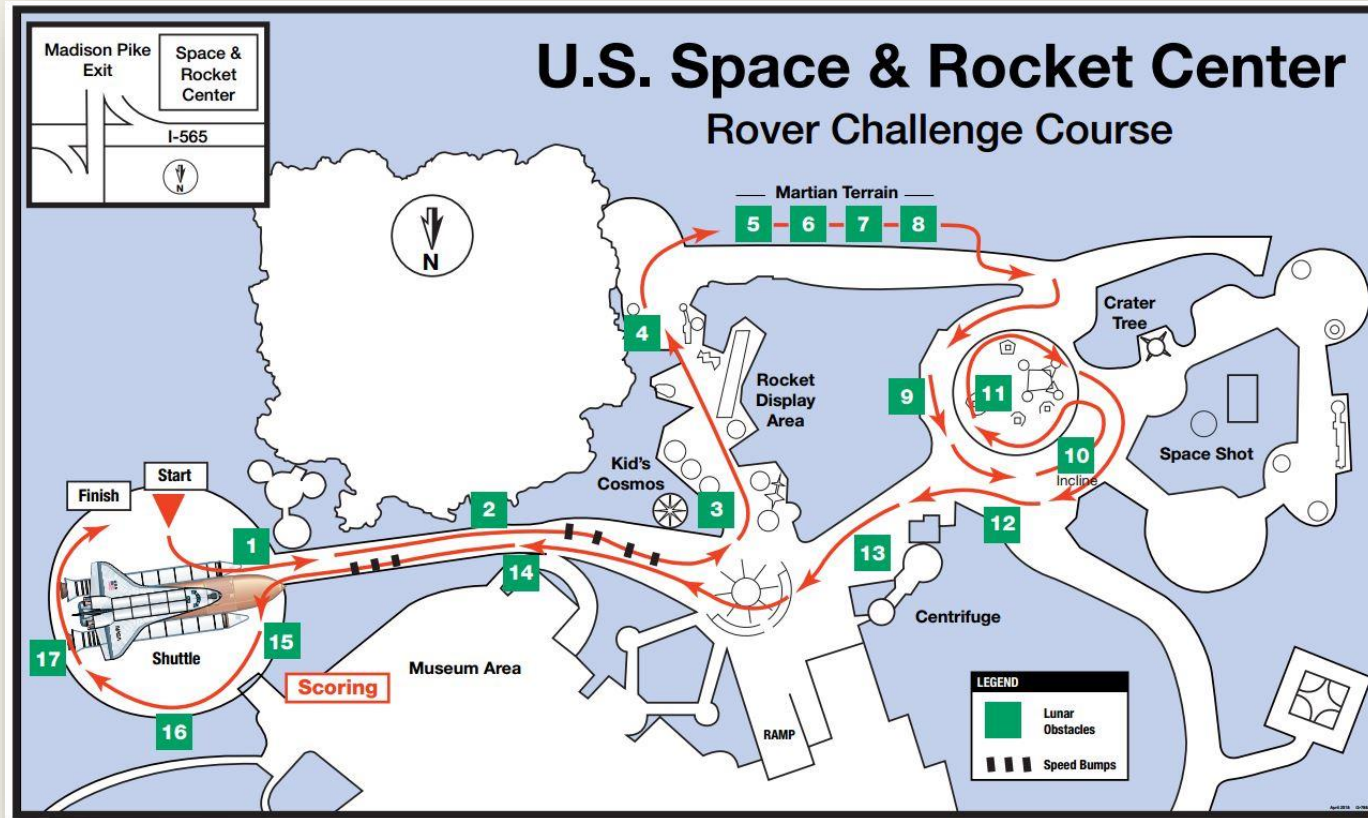


## Objective

- Vehicle can support load of two team members.
- Ability to fold into 5'x5'x5' cube
- Pass safety requirements prior to race.



# Course Obstacles



1. Undulating Terrain
2. Wrinkle Ridges
3. Crater with Ejecta
4. Rims of Craters
5. Martian Terrain – Butte
6. Linear Gully
7. Outcrops
8. Sand Dunes
9. Crevasses
10. Steep Incline
11. Lava Flow with Craters
12. Tilted Craters
13. Asteroid Impact
14. Collapsed Fault
15. Loose Regolith
16. Hummocky Area
17. Erosion Bed

# Overall Design



- Lightweight
- Strong
- Cost effective material
- Ease of manufacture
- Cater design to obstacles

# Wheels

- Modular Design
- HDPE and Steel Construction
- Jig ensured proper construction and roundness



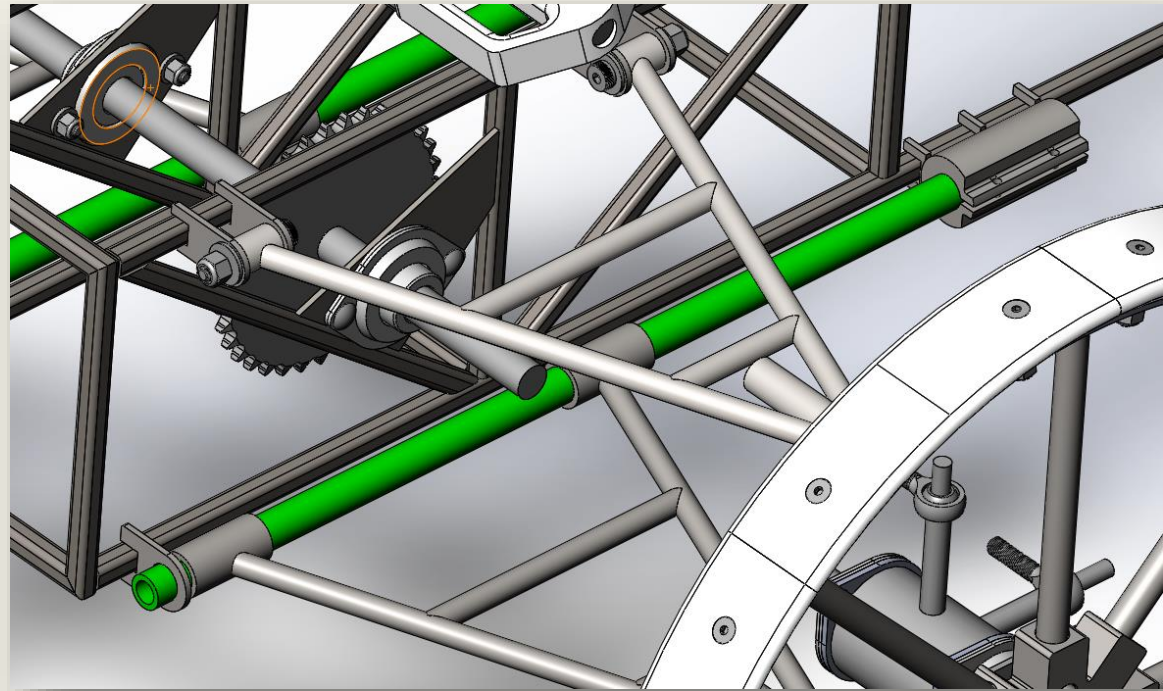
# Wheels

- CNC cut HDPE
- Hub cut with plasma
- Used jig to assemble
- Welded and bolted assembly



# Suspension

- Torsion bar suspension
- Light weight
- Compact fit
- Ease of manufacture
- Low cost



# Suspension

- Set screws insufficient
- Welded joints
- Potential improvements:
  - *Ground clearance*
  - *Adjustability*



# Drivetrain



- Low gear ratio
- Coaster brake hub
- Two chain drive line
- Four wheel drive
- Splined slip shafts

# Drivetrain



- Two wheel drive
- Chain guides and tensioners
- Bicycle chain



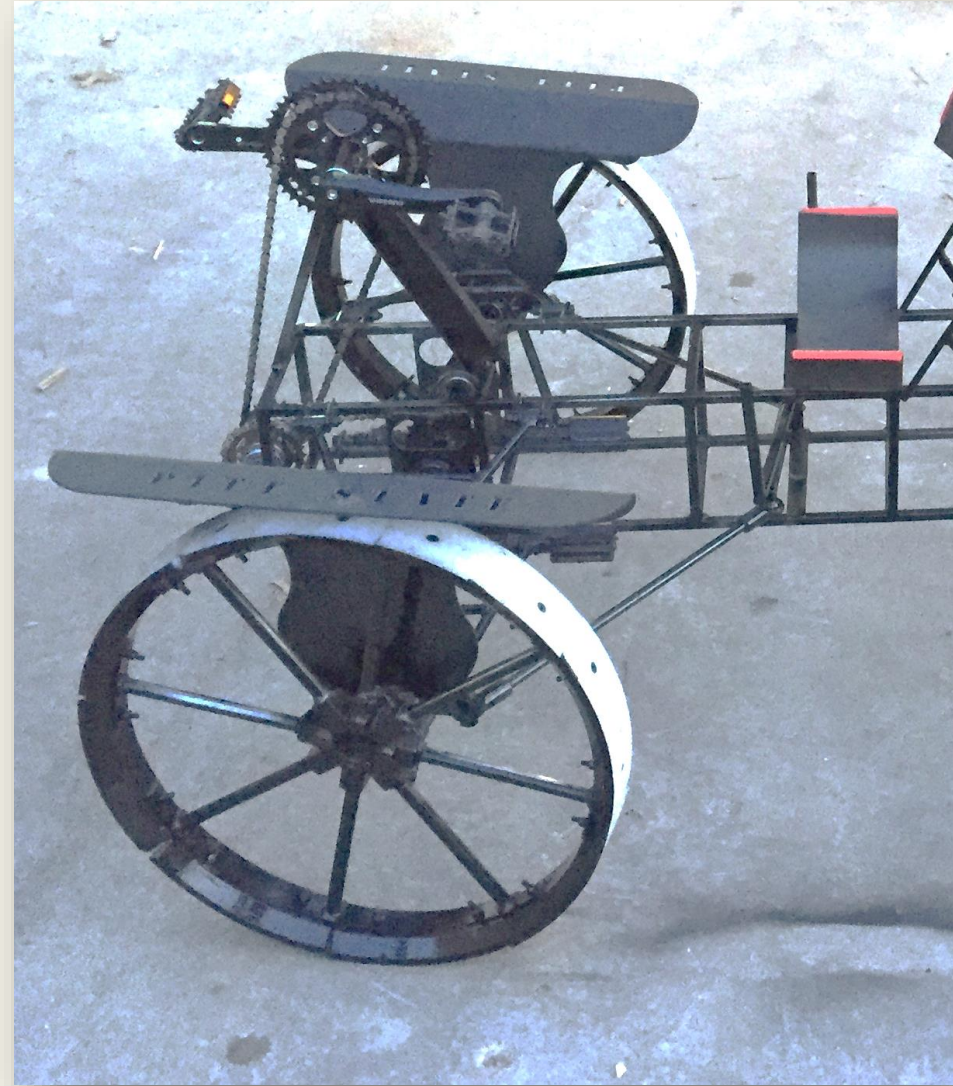
# Steering

- Rods connecting handlebars and wheels
- Plastic bushings
- Ball joints at steering column
- Heim joints at wheels
- Two attachment points to frame

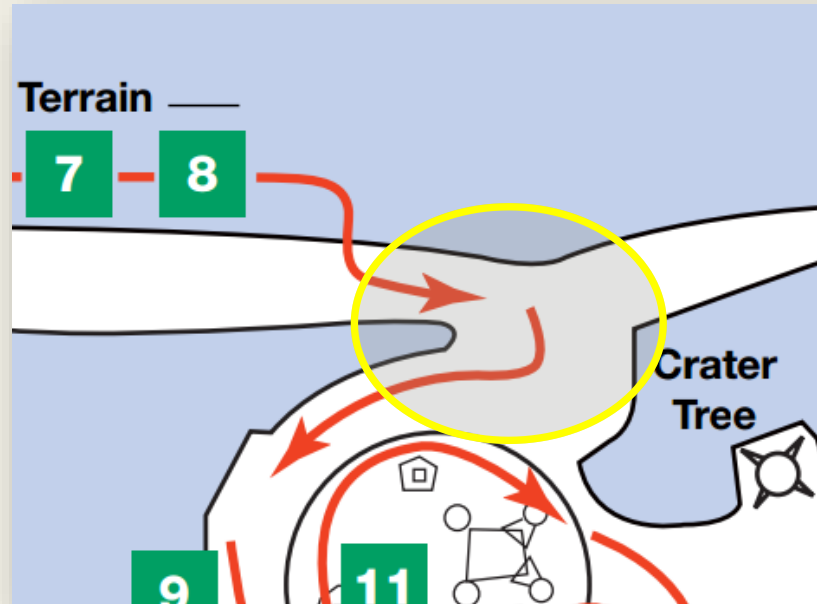


# Steering

- Original failed design
- Too big of an angle
- Tie rods binding
- Pushed forward rather than linear



# Steering



- Linear system
- Handlebar extensions
- 10 ft. turning radius



# Overall Result

- 17<sup>th</sup> place out of 57 Universities
- 184 lbs.
- Schedule strained
- Team communication



# Lessons Learned



## ■ Design

- *Use larger diameter wheels*
- *Shorter pedal cranks/ability to ratchet pedals*
- *Smaller gear ratio*

## ■ Manufacturing Plan

- *Not cut raw material until ready to build sub-assembly*
- *Better way of keeping track of what is built already*
- *Communication*
- *Spend more time aligning drive train*
- *Spend more time on routing sheets*

# Lessons Learned

- Changes to Rover
  - *Not use torsion bar suspension*
  - *Adjust material sizes and thickness*
- Advice for next year
  - *Start fundraising early*
  - *Vote on team captain*
  - *Purchase material ASAP*
  - *Plan for extra time and money*
  - *Be excited. It is a lot of fun.*



# Thank you

